

# **Trimble Access™ Mines**

## **User Guide**

Version 2025.10  
Revision A  
April 2025

# Contents


- Trimble Mines software ..... 3**
  - Adding data to the job ..... 4
  - To auto stake a centerline ..... 4
  - To auto stake a grade line ..... 6
  - To auto stake laser lines ..... 8
  - To auto stake laser lines from a centerline ..... 10
  - To project a line ..... 12
  - To auto stake blast holes ..... 14
  - To auto stake pivot points ..... 16
  - Auto stake settings ..... 18
  - Legal information ..... 20

# Trimble Mines software

Trimble® Mines software is specifically designed for surveying in mining environments.


Use Mines to:

- Define and auto stake center, grade, and laser lines to align a drilling rig.
- Auto stake predefined blast hole positions.
- Auto stake predefined pivot points to position a drilling rig.
- Generate reports for the surveyed mine.

To use Mines, you must switch to the Mines app. To switch between applications, tap  and tap the name of the app you are currently using, and then select the application to switch to.

**TIP** – The Mines app includes the full **Cogo** menu from General Survey so that you can carry out coordinate geometry (cogo) functions without having to switch to General Survey. You can also access some of these cogo functions from the tap and hold menu in the map. For information on all available cogo functions, refer to the *Trimble Access General Survey User Guide*.

When starting a survey you are prompted to select the survey style you have configured for your equipment. To learn more about survey styles and related connection settings refer to the appropriate topics in the *Trimble Access Help*.

To switch between applications, tap  and tap the name of the app you are currently using, and then select the application to switch to.


To automatically stake out...	Select...
A line at set intervals along the mine back (ceiling).	<a href="#">Centerline</a>
A line at set intervals along the mine walls.	<a href="#">Grade line</a>
Intersection points between the mine walls and a line defined by two points.	<a href="#">Laser lines</a>
Intersection points between the mine wall and laser lines defined at right angles relative to the centerline at a defined interval.	<a href="#">Laser lines offset from a centerline</a>
The intersection point between a mine face and a line.	<a href="#">Project line</a>
The intersection point between a mine face and a line defined by two points.	<a href="#">Blast holes</a>
Pivot points that have been projected up onto the mine back.	<a href="#">Pivot points</a>



**TIP** – To watch how to stake out different lines and points and how to configure options, take a look at the [Trimble Access Mines playlist](#) on the [Trimble Access YouTube channel](#).

## Adding data to the job

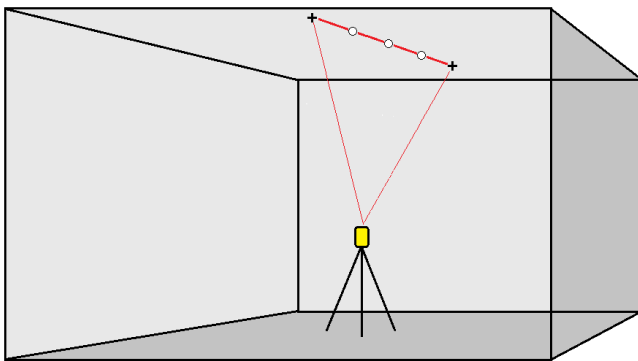
You can add linework to the job from a DXF or STR (Surpac) file.



Points can be imported into the job, linked to the current job, or imported into another job and that job linked to the current job. To import points, tap  and select **Job** and then tap **Import**. Depending on the features you want to stake, the points in the job must meet the following criteria:

- Pivot points must be identified by either a prefix or suffix in their point name.
- Laser line points must be matched pairs of points defined using their point names. A point must have a prefix or suffix to identify it as the left or the right hand end of the line. The remainder of the point name must be identical for a match pair to be found. For example, if the Left points prefix is L and the Right points prefix is R, then the following points would be identified as matched pairs: L1–R1, L15–R15, L101–R101, etc.
- Blast hole points must be matched pairs of points defined using their point names. A point must have a prefix or suffix to identify it as the blast hole collar or toe. The remainder of the point name must be identical for a match pair to be found. For example, if the collar points suffix is C and the toe points suffix is T, then the following points would be identified as matched pairs: 1C–1T, 15C–15T, A1C–A1T, etc.

## To auto stake a centerline

Automatically stake out centerlines along the mine back (ceiling). You can save the located centerline points for later use as pivot point locations.



1. To create the centerline:
    - In the map, select the line and then tap **Auto stake / Centerline**.
    - Tap  and select **Auto stake / Centerline** and select the start and end points.  
When selecting points, select them from the map or tap  for other selection methods.
- To reverse the direction of the line, tap **Swap**.

2. Then:
  - a. Define an **Interval** for staking the line.
  - b. If required, define offsets. The line can be offset by a:
    - **Horizontal offset** – applied left or right of the line
    - **Vertical offset** – applied above or below the line

These offsets are used to adjust the design positions.
  - c. To define the stake out start point, do one of the following:
    - Point the instrument laser toward the location where you want to start stakeout and select the **Start auto stake at laser position** check box. The software calculates the distance from the design start point and automatically populates the distance in the **Station offset** field.
    - Enter the distance from the design start point in the **Station offset** field.
  - d. To extend the line, enter the extension distance in the **Extend beyond end point** field. To shorten the line, enter a negative value in this field.
  - e. Tap **Next**.
3. Enter values for the **Point details**, **Position tolerance**, and **Settings** or accept the default values. See [Auto stake settings, page 18](#). Position tolerance values refer to the tolerance when searching for the next position on the mine surface. Position tolerance in this context does not refer to the precision or accuracy of the measured point. Tap **Next**.
4. Tap **Next**.

**TIP** – If the instrument fails to point in the correct direction, during the **Start delay** period, you can manually point the instrument in the correct direction.

The instrument turns to the design point, measures a position and then checks this position against the defined tolerances. If it is outside the tolerances it turns to a new position and repeats the process until a position within tolerance is found, or the maximum number of iterations is reached.

The software will use the previous position to reduce the number of iterations required to find the next position. However if a position is not found within tolerance the software will use the design position of the previous position to reduce the number of iterations required to find the next position.

- When a position is found within tolerance, the **Mark point** event sounds and:
  - If the instrument has a tracklight, the laser pointer **and** the tracklight **flash** for the period defined in the **Mark delay** field.
  - If the instrument is a Trimble SX12 scanning total station, the instrument changes to **STD** mode and the laser pointer **stops flashing** and moves to position itself at the EDM location. The laser pointer **changes to solid** while the Target Illumination light (TIL) flashes for the period defined in the **Mark delay** field. When the point is stored

the instrument automatically returns to **TRK** mode and the laser pointer resumes flashing.

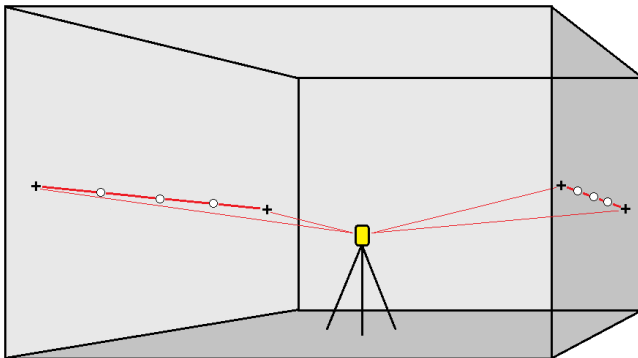
At the end of the **Mark delay** period the instrument auto stakes the next point. Tap **Pause** to temporarily halt the auto stake process. Use the **Prev** and **Next** softkeys to skip to the previous or next point.

- While the software is iterating to find a point within tolerance of the target, tap **Pause** to temporarily halt the iteration process. The software switches the instrument to tracking mode and shows the stakeout deltas, which indicate the direction the instrument EDM needs to go to reach the target. A value shown in red indicates the deltas are out of tolerance. Use the arrow keys on the controller or the arrow keys on the video screen to move the instrument EDM closer to the target. Once the delta values are shown in black tap **Store** to store the record, restart the auto stakeout sequence, and move to the mark point step.
  - If a point within tolerance cannot be found, the point is skipped.
5. When the end of the line is reached, the **Results** screen shows the number of points staked and the number of points skipped.

If any points were skipped, tap the **Retry** softkey to retry auto staking the skipped points. Tap the **Tolerance** softkey to change the tolerance settings, if required.

## To auto stake a grade line

Automatically stake out grade line points along the mine face using a design file or by measuring points at set intervals along the mine walls. You can save the located grade line points for later use as laser line point locations.



1. To create the grade line:
  - In the map, select the line and then tap **Auto stake / Grade line**.
  - Tap **≡** and select **Auto stake / Grade line** and select the start and end points.

When selecting points, select them from the map or tap **►** for other selection methods.

To reverse the direction of the line, tap **Swap**.

## 2. Then:

- a. Define an **Interval** for staking the line.
- b. If required, define offsets. The line can be offset by a:
  - **Horizontal offset** – applied left or right of the line
  - **Vertical offset** – applied above or below the line

These offsets are used to adjust the design positions.

- c. To define the stake out start point, do one of the following:
    - Point the instrument laser toward the location where you want to start stakeout and select the **Start auto stake at laser position** check box. The software calculates the distance from the design start point and automatically populates the distance in the **Station offset** field.
    - Enter the distance from the design start point in the **Station offset** field.
  - d. To extend the line, enter the extension distance in the **Extend beyond end point** field. To shorten the line, enter a negative value in this field.
  - e. Tap **Next**.
3. Enter values for the **Point details**, **Position tolerance**, and **Settings** or accept the default values. See [Auto stake settings, page 18](#). Position tolerance values refer to the tolerance when searching for the next position on the mine surface. Position tolerance in this context does not refer to the precision or accuracy of the measured point. Tap **Next**.
  4. Tap **Next**.

**TIP** – If the instrument fails to point in the correct direction, during the **Start delay** period, you can manually point the instrument in the correct direction.

The instrument turns to the design point, measures a position and then checks this position against the defined tolerances. If it is outside the tolerances it turns to a new position and repeats the process until a position within tolerance is found, or the maximum number of iterations is reached.

The software will use the previous position to reduce the number of iterations required to find the next position. However if a position is not found within tolerance the software will use the design position of the previous position to reduce the number of iterations required to find the next position.

- When a position is found within tolerance, the **Mark point** event sounds and:
  - If the instrument has a tracklight, the laser pointer **and** the tracklight **flash** for the period defined in the **Mark delay** field.
  - If the instrument is a Trimble SX12 scanning total station, the instrument changes to **STD** mode and the laser pointer **stops flashing** and moves to position itself at the EDM location. The laser pointer **changes to solid** while the Target Illumination light (TIL) flashes for the period defined in the **Mark delay** field. When the point is stored

the instrument automatically returns to **TRK** mode and the laser pointer resumes flashing.

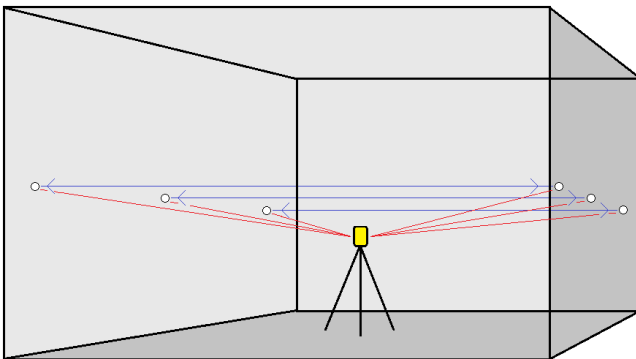
At the end of the **Mark delay** period the instrument auto stakes the next point. Tap **Pause** to temporarily halt the auto stake process. Use the **Prev** and **Next** softkeys to skip to the previous or next point.

- While the software is iterating to find a point within tolerance of the target, tap **Pause** to temporarily halt the iteration process. The software switches the instrument to tracking mode and shows the stakeout deltas, which indicate the direction the instrument EDM needs to go to reach the target. A value shown in red indicates the deltas are out of tolerance. Use the arrow keys on the controller or the arrow keys on the video screen to move the instrument EDM closer to the target. Once the delta values are shown in black tap **Store** to store the record, restart the auto stakeout sequence, and move to the mark point step.
  - If a point within tolerance cannot be found, the point is skipped.
5. When the end of the line is reached, the **Results** screen shows the number of points staked and the number of points skipped.

If any points were skipped, tap the **Retry** softkey to retry auto staking the skipped points. Tap the **Tolerance** softkey to change the tolerance settings, if required.

## To auto stake laser lines

Automatically stake out laser line points along the mine face using a design file or by calculating new laser line locations along the grade line.




1. To create the laser lines:

- In the map, select the line(s) and then tap **Auto stake / Laser lines**.

When you select laser lines from the map by dragging a box around them, the laser line definitions are now listed in the order they are defined in the file. When you select them by tapping them individually in the map, the laser line definitions are still shown in the order selected in which you selected them in the map.



- Tap  and select **Auto stake / Laser lines** and select the points:
  - a. Set the **Selection method** to either **Prefix** or **Suffix** so it matches the naming convention of the points in your job.
  - b. Enter the **Left points prefix/suffix** and the **Right points prefix/suffix**. Tap **Next**.  
All matching pairs in the job with the correct prefix/suffix are listed.  
  
Matched pairs of points must be defined using their point names. A point must have a prefix or suffix to identify it as the left or the right hand end of the line. The remainder of the point name must be identical for a match pair to be found. For example, if the Left points prefix is L and the Right points prefix is R, then the following points would be identified as matched pairs: L1–R1, L15–R15, L101–R101, etc.
  - c. If required, select and delete any points that do not require staking.
  - d. Tap **Next**.

To reverse the direction of the line, tap **Swap**.

2. Enter values for the **Point details** and **Settings**, or accept the default values. Tap **Next**.
3. Tap **Next**.

The Mines software stakes all the points on the left, starting with the first line and finishing on the last. It then stakes all the points on the right side, starting with the last line and finishing on the first.

**TIP** – If the instrument fails to point in the correct direction, during the **Start delay** period, you can manually point the instrument in the correct direction.

The instrument turns to the design point, measures a position and then checks this position against the defined tolerances. If it is outside the tolerances it turns to a new position and repeats the process until a position within tolerance is found, or the maximum number of iterations is reached.

The software will use the previous position to reduce the number of iterations required to find the next position. However if a position is not found within tolerance the software will use the design position of the previous position to reduce the number of iterations required to find the next position.

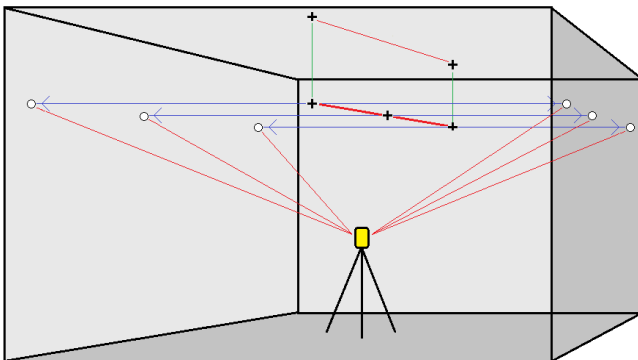
- When a position is found within tolerance, the **Mark point** event sounds and:
  - If the instrument has a tracklight, the laser pointer **and** the tracklight **flash** for the period defined in the **Mark delay** field.
  - If the instrument is a Trimble SX12 scanning total station, the instrument changes to **STD** mode and the laser pointer **stops flashing** and moves to position itself at the EDM location. The laser pointer **changes to solid** while the Target Illumination light (TIL) flashes for the period defined in the **Mark delay** field. When the point is stored the instrument automatically returns to **TRK** mode and the laser pointer resumes flashing.

At the end of the **Mark delay** period the instrument auto stakes the next point. Tap **Pause** to temporarily halt the auto stake process. Use the **Prev** and **Next** softkeys to skip to the previous or next point.

- While the software is iterating to find a point within tolerance of the target, tap **Pause** to temporarily halt the iteration process. The software switches the instrument to tracking mode and shows the stakeout deltas, which indicate the direction the instrument EDM needs to go to reach the target. A value shown in red indicates the deltas are out of tolerance. Use the arrow keys on the controller or the arrow keys on the video screen to move the instrument EDM closer to the target. Once the delta values are shown in black tap **Store** to store the record, restart the auto stakeout sequence, and move to the mark point step.
  - If a point within tolerance cannot be found, the point is skipped.
4. When the process has finished, the **Results** screen shows the number of points staked and the number of points skipped.

## To auto stake laser lines from a centerline

Automatically stake out laser lines offset from a centerline. The laser lines are defined at regular intervals at right angles relative to the centerline.



1. To create the centerline:
  - In the map, select the line(s) and then tap **Auto stake / Laser lines offset from CL**.
  - Tap **≡** and select **Auto stake / Laser lines offset from CL** and select the start and end points.

When selecting points, select them from the map or tap ► for other selection methods.

To reverse the direction of the line, tap **Swap**.

2. Then:
  - a. Define an **Interval** for staking the line.
  - b. If required, define offsets. The centerline can be offset by a:
    - **Vertical offset** – applied above or below the centerline
    - **Station offset** – applied backward or forward along the centerline

These offsets are used to calculate the design positions.
  - c. To extend the centerline, enter the extension distance in the **Extend beyond end point** field. To shorten the centerline, enter a negative value in this field.
  - d. Tap **Next**.
3. Review the defined laser lines. Select and delete any lines that do not require staking. Tap **Next**.
4. Enter values for the **Point details** and **Settings**, or accept the default values. Tap **Next**.
5. To aid in the auto stakeout of the laser lines you are prompted to aim and measure a position on the right side of the mine. Repeat when prompted for the left side.
6. Tap **Next**.

The Mines software stakes all the points on the left, starting with the first line and finishing on the last. It then stakes all the points on the right side, starting with the last line and finishing on the first..

**TIP** – If the instrument fails to point in the correct direction, during the **Start delay** period, you can manually point the instrument in the correct direction.

The software will use the previous position to reduce the number of iterations required to find the next position. However if a position is not found within tolerance the software will use the design position of the previous position to reduce the number of iterations required to find the next position.

- When a position is found within tolerance, the **Mark point** event sounds and:
  - If the instrument has a tracklight, the laser pointer **and** the tracklight **flash** for the period defined in the **Mark delay** field.
  - If the instrument is a Trimble SX12 scanning total station, the instrument changes to **STD** mode and the laser pointer **stops flashing** and moves to position itself at the EDM location. The laser pointer **changes to solid** while the Target Illumination light (TIL) flashes for the period defined in the **Mark delay** field. When the point is stored the instrument automatically returns to **TRK** mode and the laser pointer resumes flashing.

At the end of the **Mark delay** period the instrument auto stakes the next point. Tap **Pause** to temporarily halt the auto stake process. Use the **Prev** and **Next** softkeys to skip to the previous or next point.

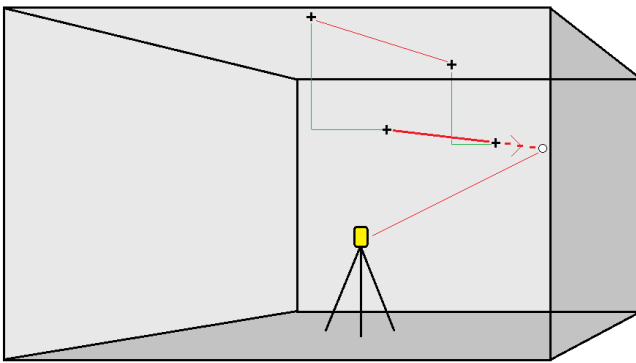
- While the software is iterating to find a point within tolerance of the target, tap **Pause** to temporarily halt the iteration process. The software switches the instrument to tracking mode and shows the stakeout deltas, which indicate the direction the instrument

EDM needs to go to reach the target. A value shown in red indicates the deltas are out of tolerance. Use the arrow keys on the controller or the arrow keys on the video screen to move the instrument EDM closer to the target. Once the delta values are shown in black tap **Store** to store the record, restart the auto stakeout sequence, and move to the mark point step.

- If a point within tolerance cannot be found, the point is skipped.
7. When the process has finished, the **Results** screen shows the number of points staked and the number of points skipped.

## To project a line

Automatically stake out projected line points at an offset from your laser line to create a new reference line between the laser line and the mine face.



1. To create the line:
  - In the map, select the line and then tap **Auto stake / Project line**.
  - Tap **≡** and select **Auto stake / Project line** and select the start and end points.

When selecting points, select them from the map or tap **►** for other selection methods.

To reverse the direction of the line, tap **Swap**.

2. If required, define offsets. The projected line can be offset by a:
  - **Horizontal offset** – applied left or right of the line
  - **Vertical offset** – applied up or down from the line
3. Tap **Next**.
4. Enter values for the **Point details**, **Position tolerance**, and **Settings** or accept the default values. See [Auto stake settings, page 18](#). Position tolerance values refer to the tolerance when searching for the next position on the mine surface. Position tolerance in this context does not refer to the precision or accuracy of the measured point. Tap **Next**.
5. Tap **Next**.

**TIP** – If the instrument fails to point in the correct direction, during the **Start delay** period, you can manually point the instrument in the correct direction.

The instrument turns to the design point, measures a position and then checks this position against the defined tolerances. If it is outside the tolerances it turns to a new position and repeats the process until a position within tolerance is found, or the maximum number of iterations is reached.

The software will use the previous position to reduce the number of iterations required to find the next position. However if a position is not found within tolerance the software will use the design position of the previous position to reduce the number of iterations required to find the next position.

- When a position is found within tolerance, the **Mark point** event sounds and:
  - If the instrument has a tracklight, the laser pointer **and** the tracklight **flash** for the period defined in the **Mark delay** field.
  - If the instrument is a Trimble SX12 scanning total station, the instrument changes to **STD** mode and the laser pointer **stops flashing** and moves to position itself at the EDM location. The laser pointer **changes to solid** while the Target Illumination light (TIL) flashes for the period defined in the **Mark delay** field. When the point is stored the instrument automatically returns to **TRK** mode and the laser pointer resumes flashing.

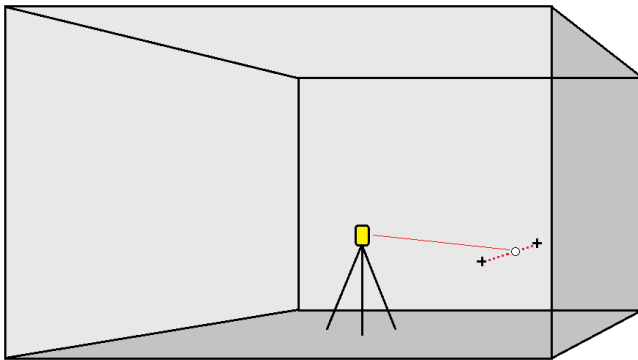
At the end of the **Mark delay** period the instrument auto stakes the next point. Tap **Pause** to temporarily halt the auto stake process. Use the **Prev** and **Next** softkeys to skip to the previous or next point.

- While the software is iterating to find a point within tolerance of the target, tap **Pause** to temporarily halt the iteration process. The software switches the instrument to tracking mode and shows the stakeout deltas, which indicate the direction the instrument EDM needs to go to reach the target. A value shown in red indicates the deltas are out of tolerance. Use the arrow keys on the controller or the arrow keys on the video screen to move the instrument EDM closer to the target. Once the delta values are shown in black tap **Store** to store the record, restart the auto stakeout sequence, and move to the mark point step.
  - If a point within tolerance cannot be found, the point is skipped.
6. When the process has finished, the **Results** screen shows the number of points staked and the number of points skipped.

## To auto stake blast holes

Automatically stake out blast hole points in the mine using a design file or by selecting them from the map or from the menu.


A blast hole point is the intersection point between the mine face and a line defined by two points – the collar point and the toe point.



### 1. To select the blast holes:

- In the map, select the line(s) that define the blast holes and then tap **Auto stake / Blast holes**.

When you select blast holes by:

- dragging a box around them in the map, the blast hole definitions are listed in the order they are defined in the file.
- tapping them individually in the map, the blast hole definitions are shown in the order in which you selected them in the map.
- Tap  and select **Auto stake / Blast holes** and select the points:
  - a. Set the **Selection method** to either **Prefix** or **Suffix** so it matches the naming convention of the points in your job.
  - b. Enter the **Collar points prefix/suffix** and the **Toe points prefix/suffix**. Tap **Next**.

All matching pairs in the job with the correct prefix/suffix are listed.

Matched pairs of points must be defined using their point names. A point must have a prefix or suffix to identify it as the blast hole collar or toe. The remainder of the point name must be identical for a match pair to be found. For example, if the collar points suffix is C and the toe points suffix is T, then the following points would be identified as matched pairs: 1C-1T, 15C-15T, A1C-A1T, etc.

### 2. Review the selected blast hole points:

- If required, select and remove any points from the list that do not require staking. Press **Ctrl** to select more than one point at a time and then tap **Remove**.

To remove several points at once you can also select a point in the list and then tap the **Remove** ↓ softkey to remove all points in the list below the selected point, or tap the **Remove** ↑ softkey to remove all points in the list above the selected point.

- To sort the points alphabetically, tap the **Collar** column header.
- To manually reorder the points, tap them in the list and drag them up or down.
- To reverse the direction of the line, select it from the list and then tap **Swap**.

Changes you make to the selected points, point order, or line direction from the list are reflected in the map.

3. Tap **Next**.
4. Enter values for the **Point details** and **Settings**, or accept the default values. Tap **Next**.
5. Tap **Next**.

**TIP** – If the instrument fails to point in the correct direction, during the **Start delay** period, you can manually point the instrument in the correct direction.

The instrument turns to the design point, measures a position and then checks this position against the defined tolerances. If it is outside the tolerances it turns to a new position and repeats the process until a position within tolerance is found, or the maximum number of iterations is reached.

The software will use the previous position to reduce the number of iterations required to find the next position. However if a position is not found within tolerance the software will use the design position of the previous position to reduce the number of iterations required to find the next position.

- When a position is found within tolerance, the **Mark point** event sounds and:
  - If the instrument has a tracklight, the laser pointer *and* the tracklight *flash* for the period defined in the **Mark delay** field.
  - If the instrument is a Trimble SX12 scanning total station, the instrument changes to **STD** mode and the laser pointer *stops flashing* and moves to position itself at the EDM location. The laser pointer *changes to solid* while the Target Illumination light (TIL) flashes for the period defined in the **Mark delay** field. When the point is stored the instrument automatically returns to **TRK** mode and the laser pointer resumes flashing.

At the end of the **Mark delay** period the instrument auto stakes the next point. Tap **Pause** to temporarily halt the auto stake process. Use the **Prev** and **Next** softkeys to skip to the previous or next point.

- While the software is iterating to find a point within tolerance of the target, tap **Pause** to temporarily halt the iteration process. The software switches the instrument to tracking mode and shows the stakeout deltas, which indicate the direction the instrument EDM needs to go to reach the target. A value shown in red indicates the deltas are out of tolerance. Use the arrow keys on the controller or the arrow keys on the video screen to

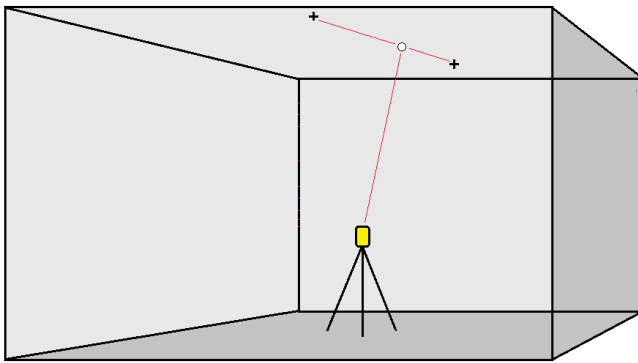
move the instrument EDM closer to the target. Once the delta values are shown in black tap **Store** to store the record, restart the auto stakeout sequence, and move to the mark point step.

- If a point within tolerance cannot be found, the point is skipped.
6. When the process has finished, the **Results** screen shows the number of points staked and the number of points skipped.

## To auto stake pivot points

Automatically stake out pivot points using a design file or by calculating new pivot point locations in the field.


The software projects the pivot point onto the mine back (ceiling) so that you can mark it before moving to the next pivot point.



1. To define the pivot points:

- In the map, select the pivot points and then tap **Auto stake / Pivot points**.

**TIP** – If the job does not already contain pivot points, you can select other points in the map and use them to define pivot points. See [To define pivot points from other map points, page 18](#).

- Tap  and select **Auto stake / Pivot points** and select the points:
  - a. Set the **Selection method** to either **Prefix** or **Suffix** so it matches the naming convention of the points in your job.
  - b. Enter the **Pivot points prefix/suffix**. Tap **Next**.  
All points in the job with the correct prefix/suffix are listed.
  - c. If required, select and delete any points that do not require staking.
  - d. Tap **Next**.

To reverse the direction of the line, tap **Swap**.

2. Enter values for the **Point details** and **Settings**, or accept the default values. Tap **Next**.



3. When prompted, aim the instrument at the mine back and then tap **Measure**. This ensures that the auto staked points will be located on the back.

The instrument turns to the design point, measures a position and then checks this position against the defined tolerances. If it is outside the tolerances it turns to a new position and repeats the process until a position within tolerance is found, or the maximum number of iterations is reached.

The software will use the previous position to reduce the number of iterations required to find the next position. However if a position is not found within tolerance the software will use the design position of the previous position to reduce the number of iterations required to find the next position.

- When a position is found within tolerance, the **Mark point** event sounds and:
  - If the instrument has a tracklight, the laser pointer **and** the tracklight **flash** for the period defined in the **Mark delay** field.
  - If the instrument is a Trimble SX12 scanning total station, the instrument changes to **STD** mode and the laser pointer **stops flashing** and moves to position itself at the EDM location. The laser pointer **changes to solid** while the Target Illumination light (TIL) flashes for the period defined in the **Mark delay** field. When the point is stored the instrument automatically returns to **TRK** mode and the laser pointer resumes flashing.

At the end of the **Mark delay** period the instrument auto stakes the next point. Tap **Pause** to temporarily halt the auto stake process. Use the **Prev** and **Next** softkeys to skip to the previous or next point.

- While the software is iterating to find a point within tolerance of the target, tap **Pause** to temporarily halt the iteration process. The software switches the instrument to tracking mode and shows the stakeout deltas, which indicate the direction the instrument EDM needs to go to reach the target. A value shown in red indicates the deltas are out of tolerance. Use the arrow keys on the controller or the arrow keys on the video screen to move the instrument EDM closer to the target. Once the delta values are shown in black tap **Store** to store the record, restart the auto stakeout sequence, and move to the next mark step.
  - If a point within tolerance cannot be found, the point is skipped.
4. When the process has finished, the **Results** screen shows the number of points staked and the number of points skipped.

## To define pivot points from other map points

Defining pivot points from points in the map is useful if the drive deviates from design and a new centerline has to be defined, requiring the pivot points defined by the intersection of the centerline with the laser lines to be recomputed.

To define pivot points from map points:

1. Select the two points that define the centerline and a laser line and then select the **Compute intersection** option from the tap and hold menu to compute a point at the intersection with the option to derive the elevation from the centerline.
2. Once the computed point is stored select the next laser line from the map and repeat the process.
3. When all pivot points have been computed you can select them ready for auto staking.

## Auto stake settings

The **Settings** form appears when you tap **Next** in the **Auto stake** form.

### Point details

Specify the **Start point** and **Point code**.

### Position tolerance

Specify the tolerances for a centerline or grade line.

**NOTE** – Position tolerance values refer to the search functions on the mine surface, not the accuracy of the position.

The **Station** tolerance value applies forward and back along the line.

The **Offset** tolerance is defined left and right of the line.

The **Grade** tolerance is defined up and down from the line and perpendicular to the line.

## Settings

The fields in the **Settings** group control the behavior of the software during auto stakeout.

### EDM timeout

To improve performance, reduce the length of the **EDM timeout**. If the instrument struggles to get a measurement due to, for example, reflective or dark surfaces, increase the **EDM timeout**.

### Mark delay

The **Mark delay** is the length of time, in seconds, that the laser pointer flashes once the position is found.

When a position is found within tolerance, the **Mark point** event sounds and:

- If the instrument has a tracklight, the laser pointer **and** the tracklight flash for the period defined in the **Mark delay** field.
- If the instrument is a Trimble SX12 scanning total station, the laser pointer **changes to solid** and the Target Illumination light (TIL) flashes for the period defined in the **Mark delay** field.

If a point within tolerance cannot be found, the point is skipped.

### Start delay

The **Start delay** gives you time to walk to the location of the first point to be marked. If the number of **Iterations** is exceeded, or the EDM times out, the point is skipped.

### Measure to define laser line elevation

Select the **Measure to define laser line elevation** check box when:

- You want to override the elevation of the points used to define the laser line.
- The points defining the laser line have no elevation or have an arbitrary elevation of 0. This can be the case when the laser lines are defined from lines in a DXF file.

If you select the **Measure to define laser line elevation** check box, you are prompted to take a measurement before the autostake process begins. The measured elevation is then used to define the elevation for the line.

# Legal information

Trimble Inc.

[www.trimble.com/en/legalspectrageospatial.com](http://www.trimble.com/en/legalspectrageospatial.com)

## Copyright and trademarks

© 2025, Trimble Inc. All rights reserved.

Trimble, the Globe and Triangle logo, Autolock, CenterPoint, FOCUS, Geodimeter, GPS Pathfinder, GPS Total Station, OmniSTAR, ProPoint, RealWorks, Spectra, Terramodel, Tracklight, Trimble Connect, Trimble RTX, and xFill are trademarks of Trimble Inc. registered in the United States and in other countries.

Access, Catalyst, FastStatic, FineLock, GX, IonoGuard, ProPoint, RoadLink, TerraFlex, TIP, Trimble Inertial Platform, Trimble Geomatics Office, Trimble Link, Trimble Survey Controller, Trimble Total Control, TRIMMARK, VISION, VRS, VRS Now, VX, and Zephyr are trademarks of Trimble Inc.

Microsoft, Excel, Internet Explorer, and Windows are either registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries.

Google and Android are trademarks of Google LLC.

The Bluetooth word mark and logos are owned by the Bluetooth SIG, Inc. and any use of such marks by Trimble Inc. is under license.

Wi-Fi and Wi-Fi HaLow are either registered trademarks or trademarks of the Wi-Fi Alliance.

All other trademarks are the property of their respective owners.

This software is based in part on the work of the Independent JPEG Group, derived from the RSA Data Security, Inc, MD5 Message-Digest Algorithm.

This product includes software developed by the OpenSSL Project for use in the OpenSSL Toolkit ([www.openssl.org/](http://www.openssl.org/)).

Trimble Access includes a number of open source libraries.

For more information, see [Open source libraries used by Trimble Access](#).

The Trimble Coordinate System Database provided with the Trimble Access software uses data from a number of third parties.

For more information, see [Trimble Coordinate System Database Open Source Attribution](#).

The Trimble Maps service provided with the Trimble Access software uses data from a number of third parties. For more information, see [Trimble Maps Copyrights](#).

For Trimble General Product Terms, go to [www.trimble.com/en/legalspectrageospatial.com](http://www.trimble.com/en/legalspectrageospatial.com).